

# Generalized Loopy 2U: A New Algorithm for Approximate Inference in Credal Networks

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# Imprecise probabilities (Walley, 1991)

Models of uncertainty about the state of a categorical variable  $X$

- A probability mass function  $P(X)$
- More generally, a *closed convex set* of probability mass functions  $K(X)$   
This is a *credal set* (Levi, 1980)
- Complete ignorance?  
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- Lower (and upper) expectation

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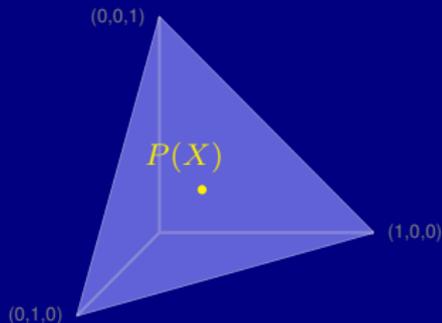
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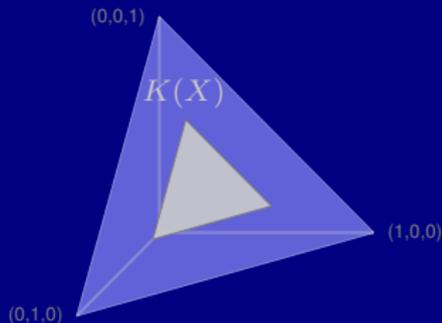


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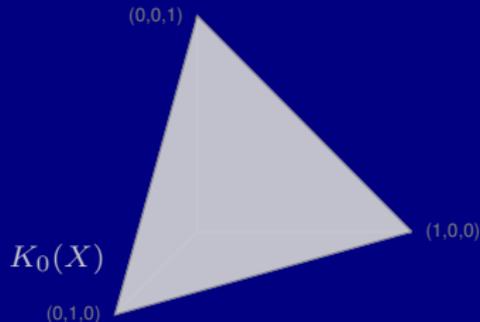


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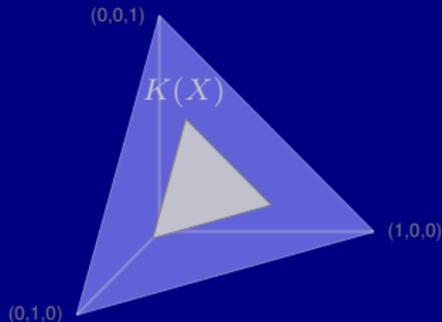


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Theorem (about representation)

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- Nodes binarization

- State of a variable as a joint state of a number of “bits”

$$X = x \iff (\tilde{X}^1 = \tilde{x}^1) \wedge (\tilde{X}^2 = \tilde{x}^2) \wedge \dots$$

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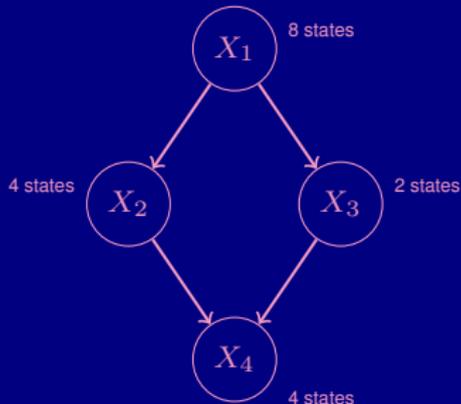
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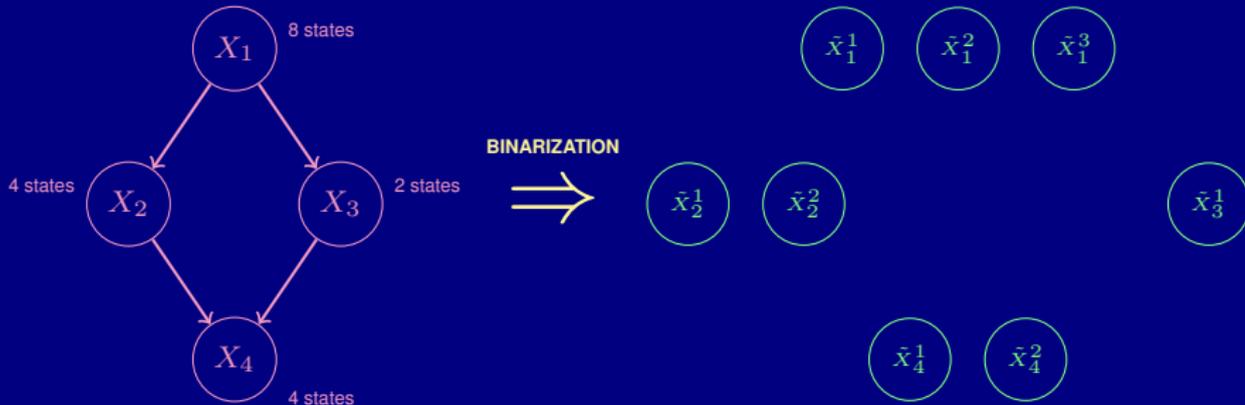
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- Arcs binarization

- For each arc between two variables, all the relative bits are linked
- The bits of the same variable are completely connected



# Binarization (graph)

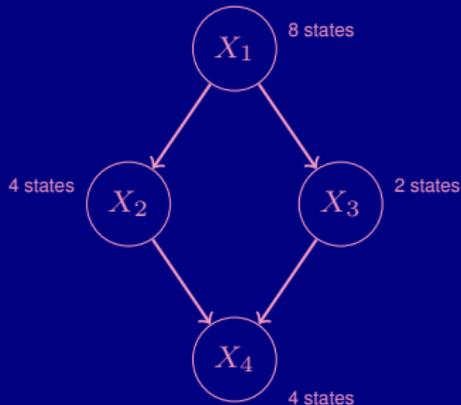
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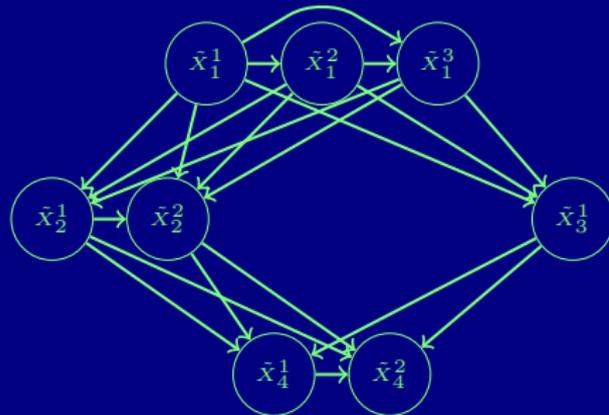
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BINARIZATION



# Binarization (probabilities)

- Bayesian nets

- All the conditional mass function  $P(\tilde{X}_i^j | \text{pa}(\tilde{X}_i^j))$  of the bits of  $X_i$  can be computed from the conditional mass function  $P(X_i | \text{pa}(X_i))$

$$P(\tilde{x}_i^j | \text{pa}(\tilde{X}_i^j)) \propto \sum_{x_i} P(x_i | \text{pa}(X_i))$$

- Credal nets

- Same calculations iterated over the conditional credal set  $K(X_i | \pi_i)$

$$\underline{P}(\tilde{x}_i^j | \text{pa}(\tilde{X}_i^j)) = \inf_{P(X_i | \text{pa}(X_i)) \in K(X_i | \text{pa}(X_i))} P(\tilde{x}_i^j | \text{pa}(\tilde{X}_i^j))$$

- A “binarized” Bayesian/credal net is obtained
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# Binarization (results)

BNs binarization is exact

- Let  $P(\mathbf{X})$  be the joint probability mass function of a BN,
- and  $\tilde{P}(\tilde{\mathbf{X}})$  the corresponding p.m.f. on the binarized BN.
- Then,  $P(\mathbf{X}) = \tilde{P}(\tilde{\mathbf{X}})$ .

CNs binarization is an outer approximation

- Let  $K(\mathbf{X})$  be the strong extension of a CN,
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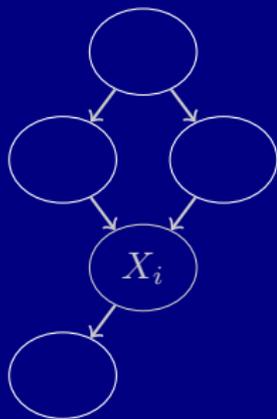
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# Decision-theoretic specification of CNs

(Antonucci & Zaffalon, PGM '06/IJAR 2008)

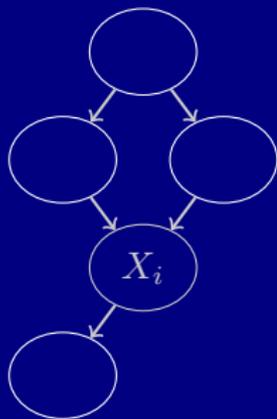
- For each  $i = 1, \dots, n$ , add a node  $T_i$ , parent of  $X_i$ , between  $X_i$  and  $\text{pa}(X_i)$
- Decision nodes  $\{T_i\}_{i=1}^n$  indexing the possible specifications of each mass function given the values of the parents
- Decision nodes can be regarded as chance nodes with a “vacuous” specification of the relative credal set
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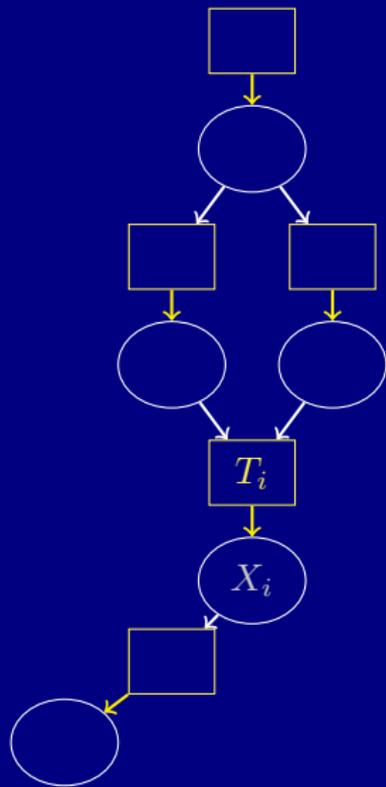
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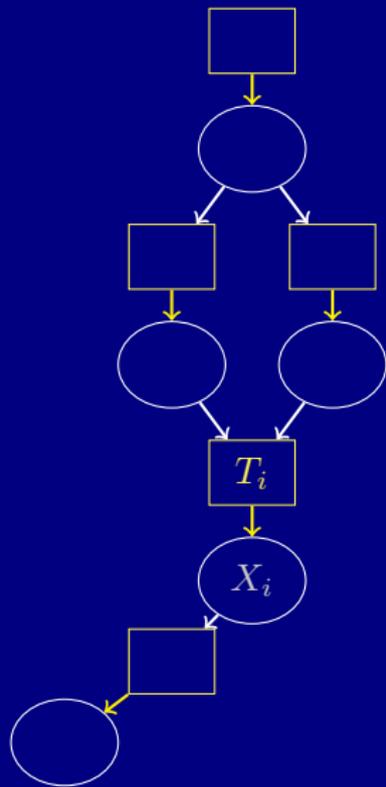
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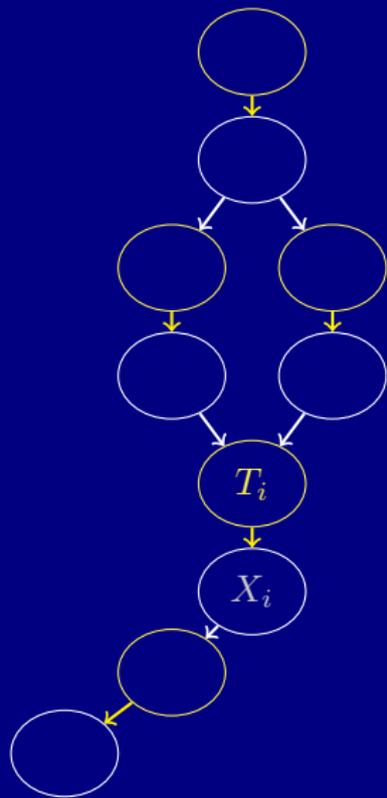
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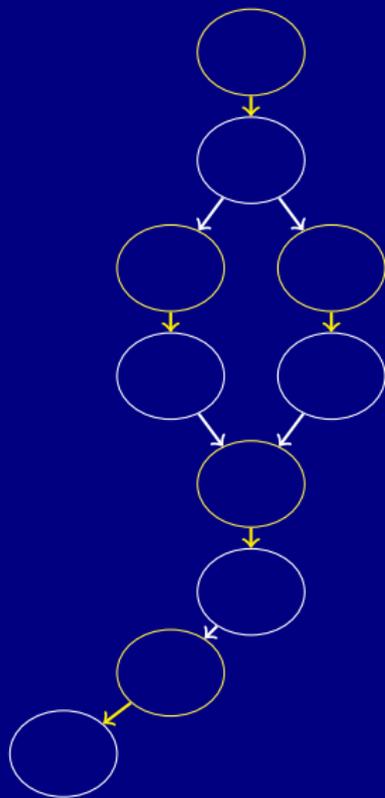
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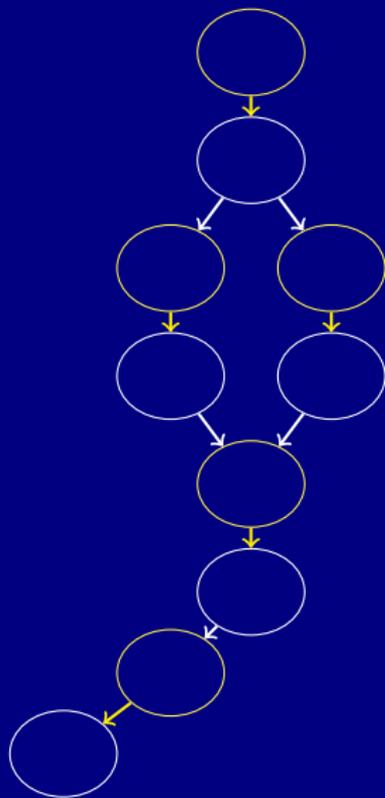
# Binarization of DT-specified CNs

- Binarization can be implemented locally
- After DT specification, the nodes are either precise or vacuous
  - For precise specifications binarization is exact (result for BNs)
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- Binarization of DT-specified CNs is exact!
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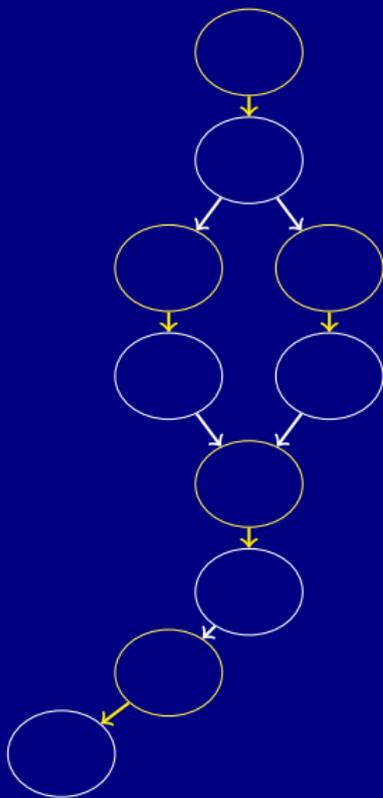
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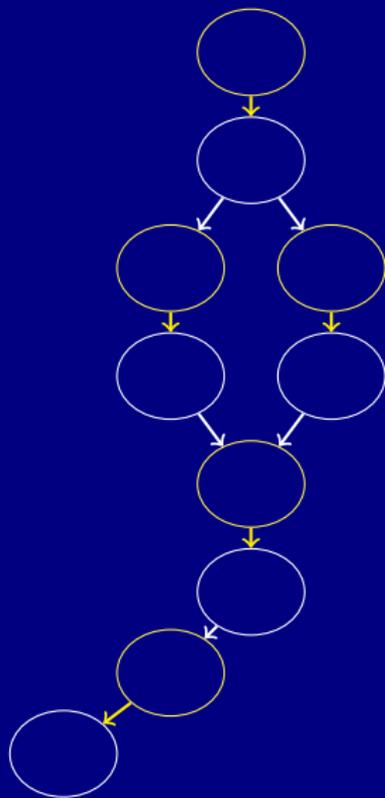
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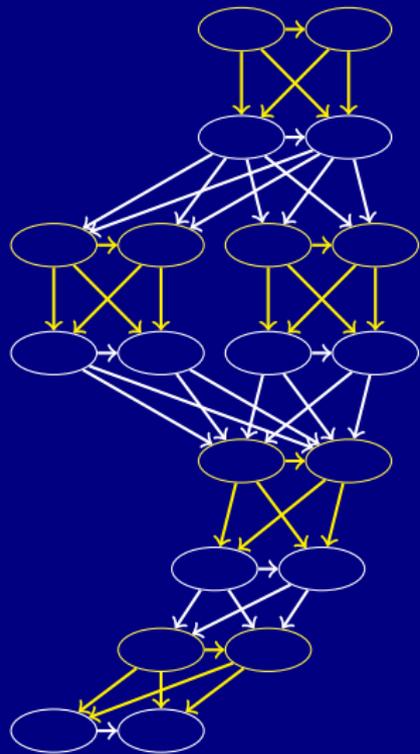
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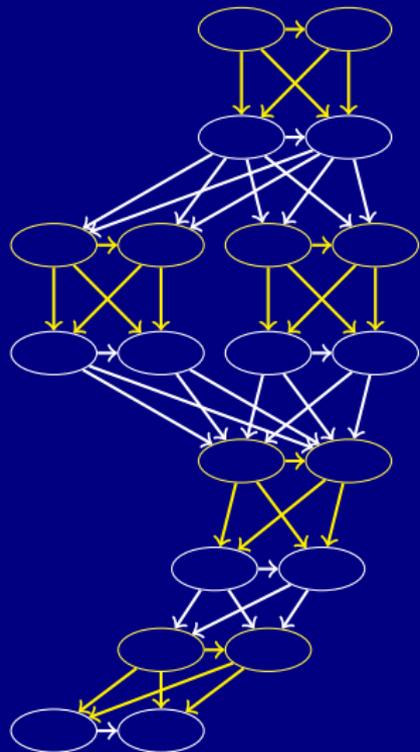
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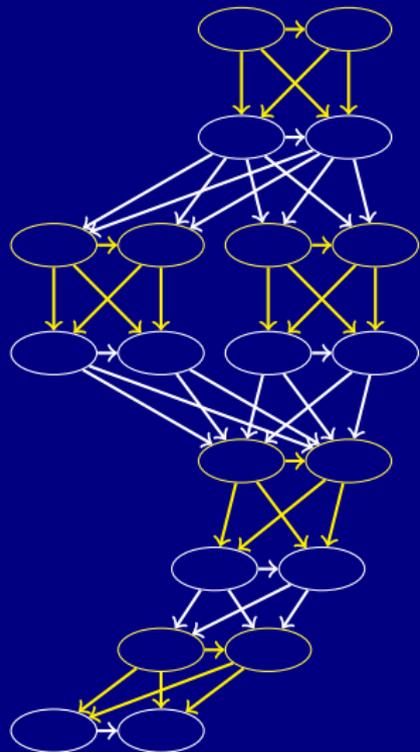
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# Generalized loopy 2U (GL2U)

- Multi-connected (non-binary) CNs?
- Binarization + L2U (twofold approx)
- DT + Bin + L2U = GL2U is better!
  - Approx only because of loopy!
  - State-of-the-art updating algorithm for CNs updating
  - Good accuracy and scalability

$O(e^{\text{indegree}_{\max}})$  is better  
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	Loc Search	GL2U	Bin+L2U
Multi-10	1.89	1.40	1.81
Multi-10	1.95	1.07	3.38
Multi-10	1.20	1.75	3.08
Multi-10	0.27	1.25	2.22
Multi-10	2.34	1.89	6.93
Multi-25	2.31	1.60	1.84
Multi-25	2.48	2.04	3.03
Polyt-50	1.12	1.93	2.89
Polyt-50	1.45	2.21	3.92
Insurance	0.55	1.17	1.75
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Multi-25	2.48	<b>2.04</b>	3.03
Polyt-50	1.12	1.93	2.89
Polyt-50	1.45	2.21	3.92
Insurance	0.55	1.17	1.75
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Alarm	2.90	<b>1.90</b>	3.02
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# Generalized loopy 2U (GL2U)

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  - State-of-the-art updating algorithm for CNs updating
  - Good accuracy and scalability

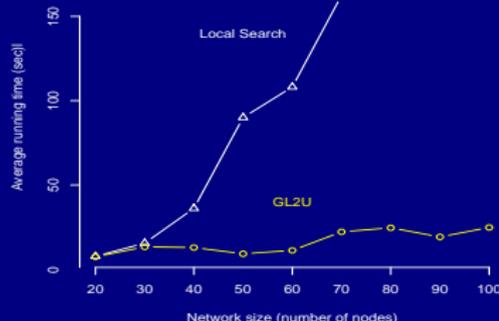
$O(e^{\text{indegree}_{\max}})$  is better than  $O(e^{\text{treewidth}})$

	Loc Search	GL2U	Bin+L2U
Multi-10	1.89	<b>1.40</b>	1.81
Multi-10	1.95	<b>1.07</b>	3.38
Multi-10	<b>1.20</b>	1.75	3.08
Multi-10	<b>0.27</b>	1.25	2.22
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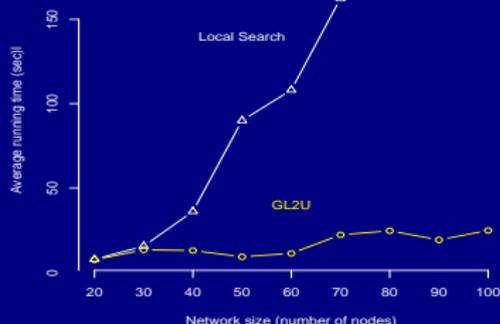
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# Conclusions and outlooks

- Exact binarization of BNs and CNs
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- The algorithm of choice for very large nets?
- A Python/C++ implementation available (ask Sun Yi)
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  - In numerical tests (G)L2U always converges.  
A formal proof of that?
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