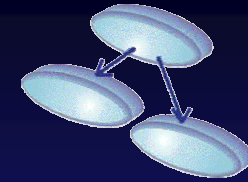




U.P.V. / E.H.U.



*Intelligent Systems Group*

# An empirical analysis of loopy belief propagation in three topologies: grids, small-world networks and random graphs

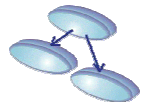
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R. Santana,  
A. Mendiburu,  
J. A. Lozano

Hirtshals, Denmark, September 17-19, 2008

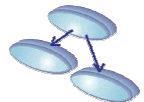
# Outline

- Motivation
- Belief Propagation
- FlexLBP
- Experiments
- Conclusions



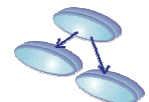
# Motivation

- Belief propagation
  - ◆ Commonly used for inference
  - ◆ Based on message-passing
  - ◆ Exact algorithm in trees
  - ◆ Good results in structures with cycles
    - ◆ Depends on different parameters
    - ◆ What about topology?



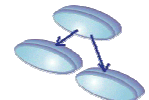
# Outline

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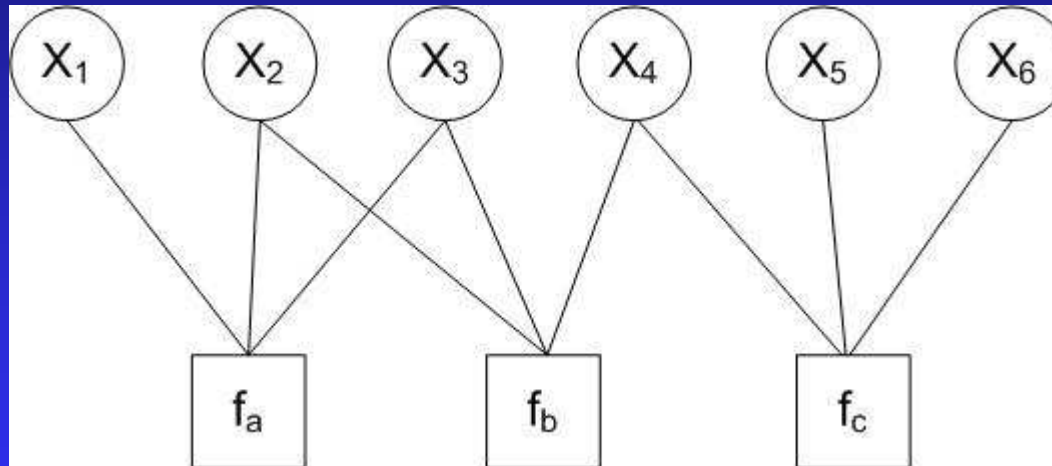
# Belief Propagation

- When used for inference
  - ◆ Marginal distribution
  - ◆ Most probable state
- Based on message-passing
  - ◆ Messages are calculated by each node and sent to other nodes



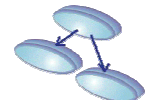
# Belief Propagation

- ◆ Can be applied to different models
  - ◆ We focus on factor graphs



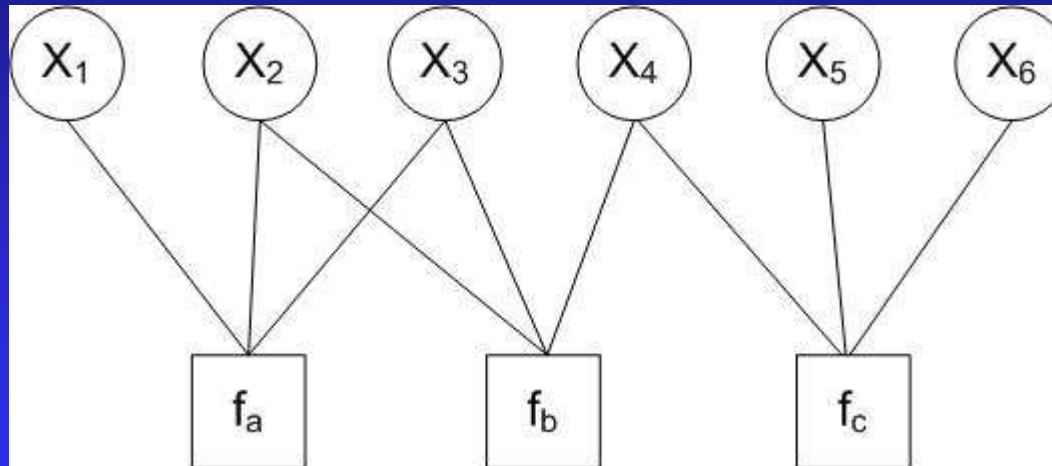
- ◆ Joint probability distribution

$$p(x_1, \dots, x_6) = \frac{1}{Z} f_a(x_1, x_2, x_3) f_b(x_2, x_3, x_4) f_c(x_4, x_5, x_6)$$



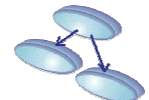
# Belief Propagation

- ◆ Each node receives, updates, and sends messages:



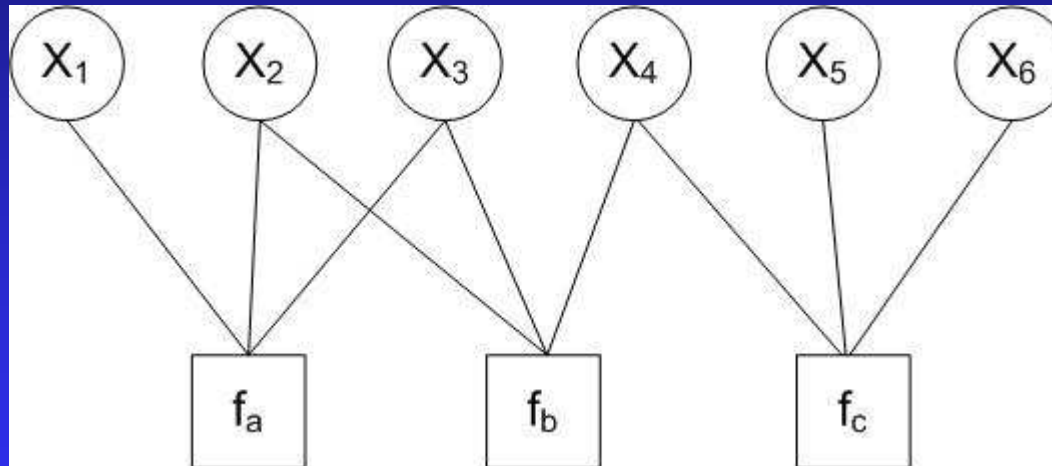
- ◆ Messages from variables to factors

$$n_{i \rightarrow a}(x_i) = \prod_{c \in N(i) \setminus a} m_{c \rightarrow i}(x_i)$$



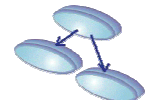
# Belief Propagation

- ◆ Each node receives, updates, and sends messages:



- ◆ Messages from variables to factors

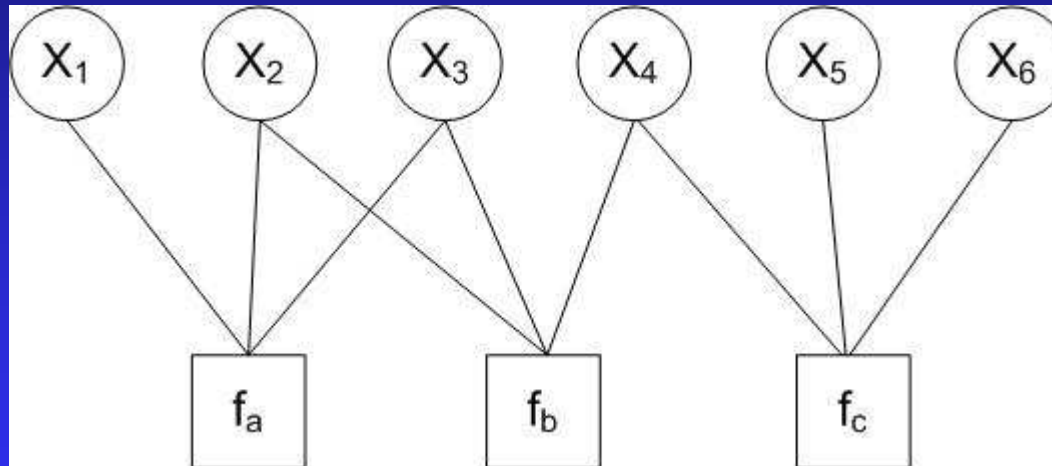
$$n_{3 \rightarrow b}(x_3) = m_{a \rightarrow 3}(x_3)$$





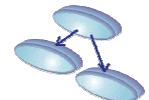
# Belief Propagation

- ◆ Each node receives, updates, and sends messages:



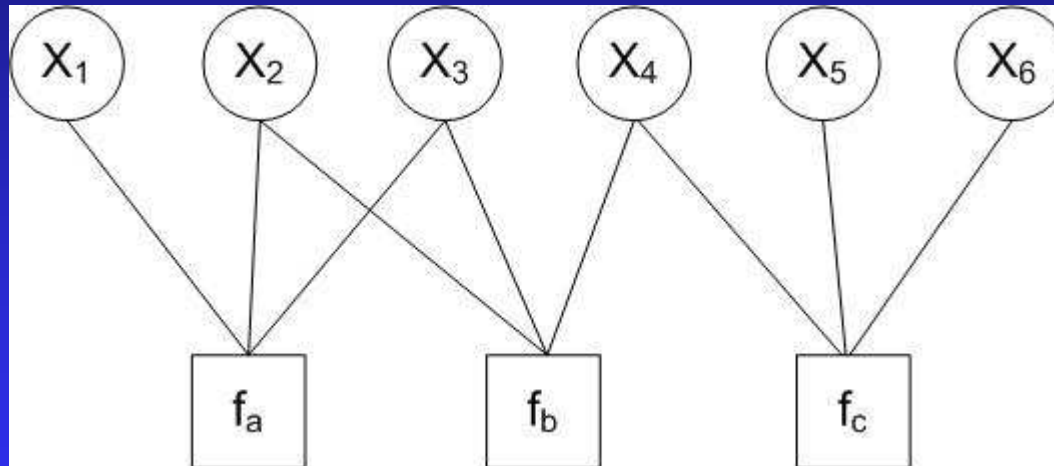
- ◆ Messages from factors to variables (inference)

$$m_{a \rightarrow i}(x_i) = \sum_{\mathcal{X}_a \setminus x_i} f_a(\mathcal{X}_a) \prod_{j \in N(a) \setminus i} n_{j \rightarrow a}(x_j)$$



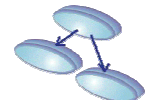
# Belief Propagation

- ◆ Each node receives, updates, and sends messages:



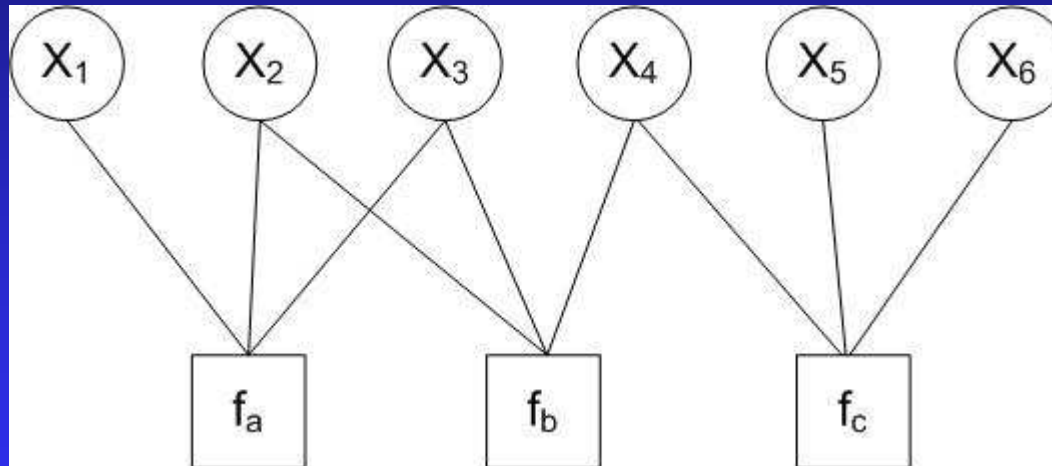
- ◆ Messages from factors to variables (inference)

$$m_{b \rightarrow 2}(x_2) = \sum_{\mathcal{X}_b \setminus x_2} f_b(x_2, x_3, x_4) n_{3 \rightarrow b}(x_3) n_{4 \rightarrow b}(x_4)$$



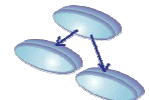
# Belief Propagation

- ◆ Each node receives, updates, and sends messages:



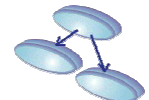
- ◆ Messages from factors to variables (optimization)

$$m_{a \rightarrow i}(x_i) = \arg \max_{\chi_a \setminus x_i} \{ f_a(\chi_a) \prod_{j \in N(a) \setminus i} n_{j \rightarrow a}(x_j) \}$$



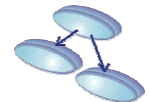
# Belief Propagation

- ◆ Analysis of Loopy Belief Propagation
  - ◆ How and when are the messages sent?
    - Scheduling policies
  - ◆ When does the algorithm finish?
    - Stopping criteria
  - ◆ Which parameters are needed?
    - Initial settings



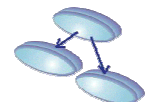
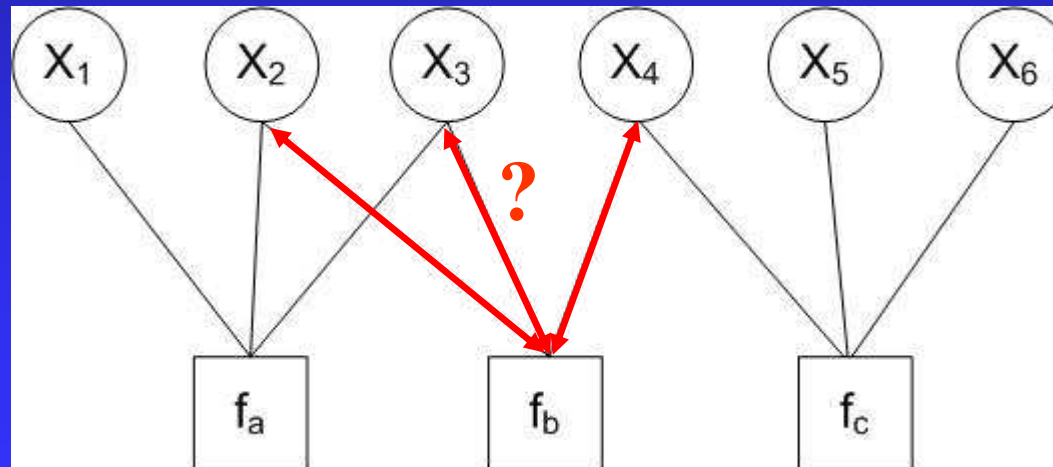
# Outline

- Motivation
- Belief Propagation
- FlexLBP
- Experiments
- Conclusions



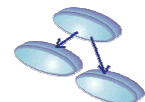
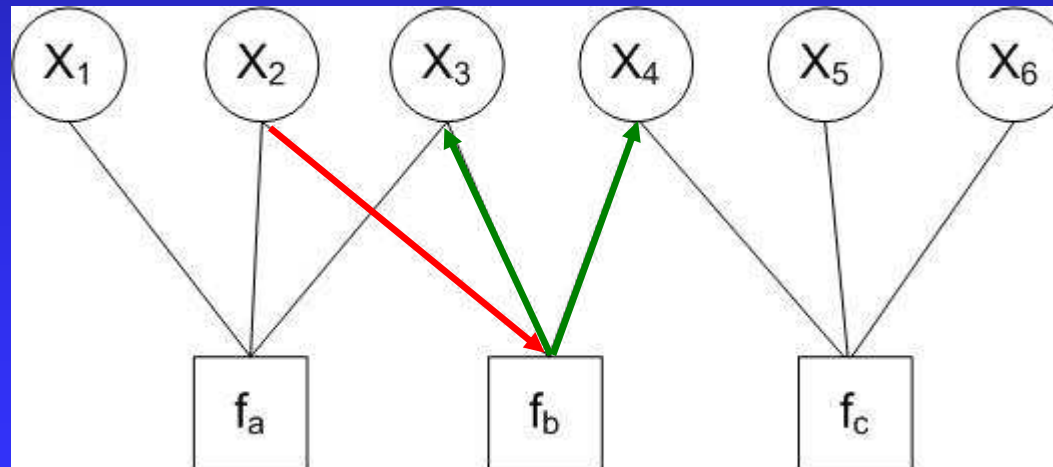
# FlexLBP

- Follows a distributed scheme
- Main characteristics:
  - ◆ Scheduling policies
    - ◆ Number-based or Set-based



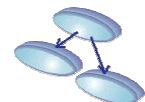
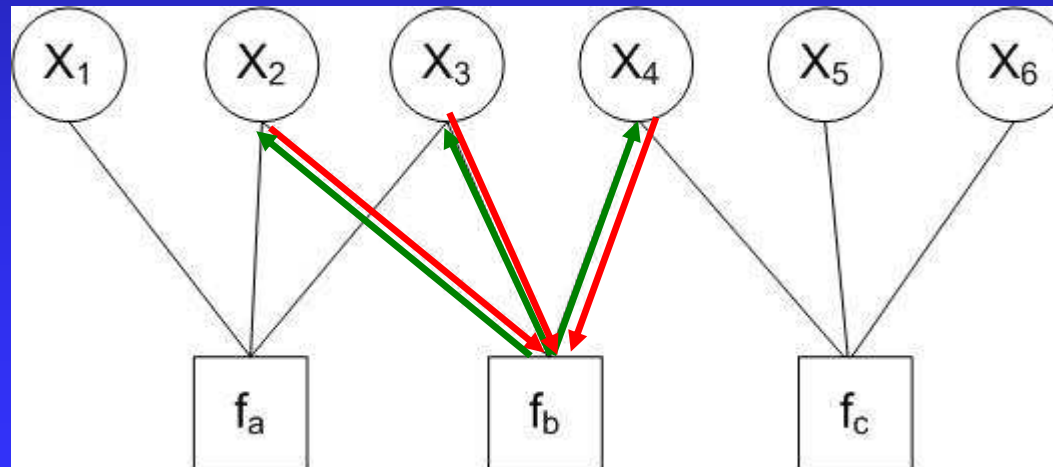
# FlexLBP

- Scheduling policies
  - ◆ Number-based
    - ◆ Send messages when  $m$  messages are received



# FlexLBP

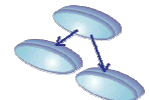
- Scheduling policies
  - ◆ Set-based
  - ◆ Recv set  $\{X_2, X_3, X_4\}$ , Send set  $\{X_2, X_3, X_4\}$





# FlexLBP

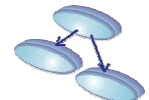
- Stopping criteria
  - ◆ Calculated by each node
  - ◆ Same message value or sequence
  - ◆ A given number of iterations
- Algorithm stops when all the nodes have finished



# FlexLBP

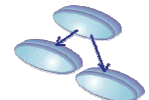
## ■ Initial settings

- ◆ Threshold
- ◆ Maximum number of iterations,
- ◆ Number of comparisons needed,
- ◆ Initial values of the messages,
- ◆ Initial ordering,
- ◆ Fixed nodes



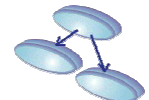
# Outline

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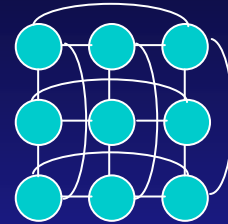
# Experiments

- FlexLBP on three different topologies
  - ◆ Grids
  - ◆ Small-world networks
  - ◆ Random graphs
- Two types of experiments
  - ◆ Arc rewiring
  - ◆ Add shortcuts

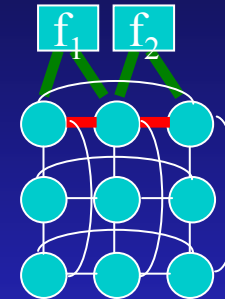


# Experiments. Arc Rewiring

Starting from a grid (7x7)

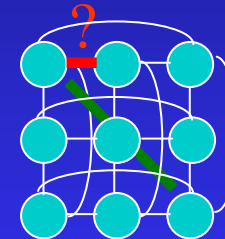


10 sets of random functions for the grid



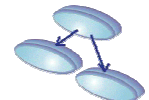
Each arc will be changed with probability  $P$   
 $P = \{0.01, 0.02, \dots, 0.1, 0.2, \dots, 0.9, 1.0\}$

100 instances for each  $P$  value

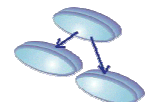
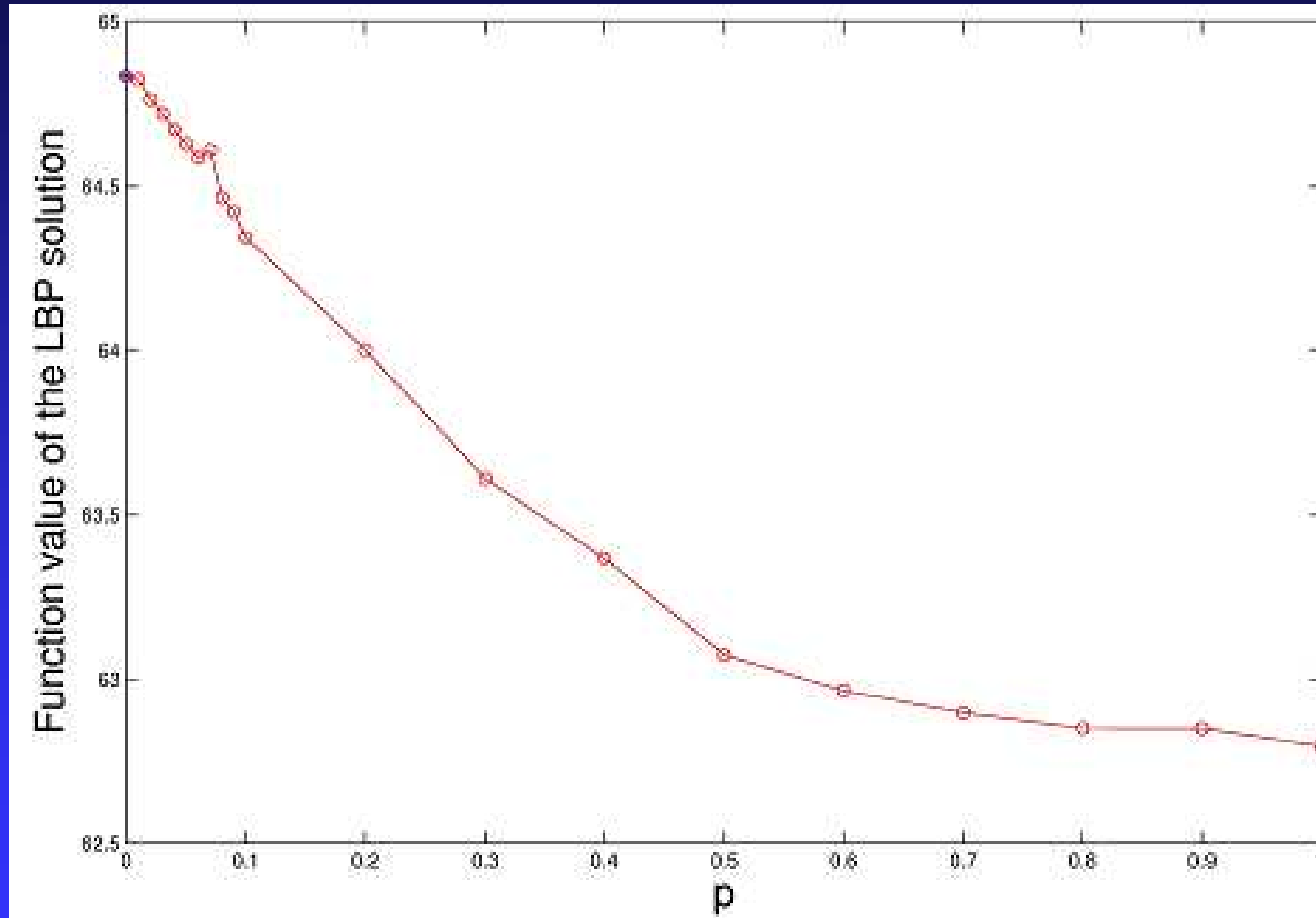


Sum-product and Max-product

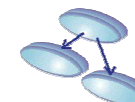
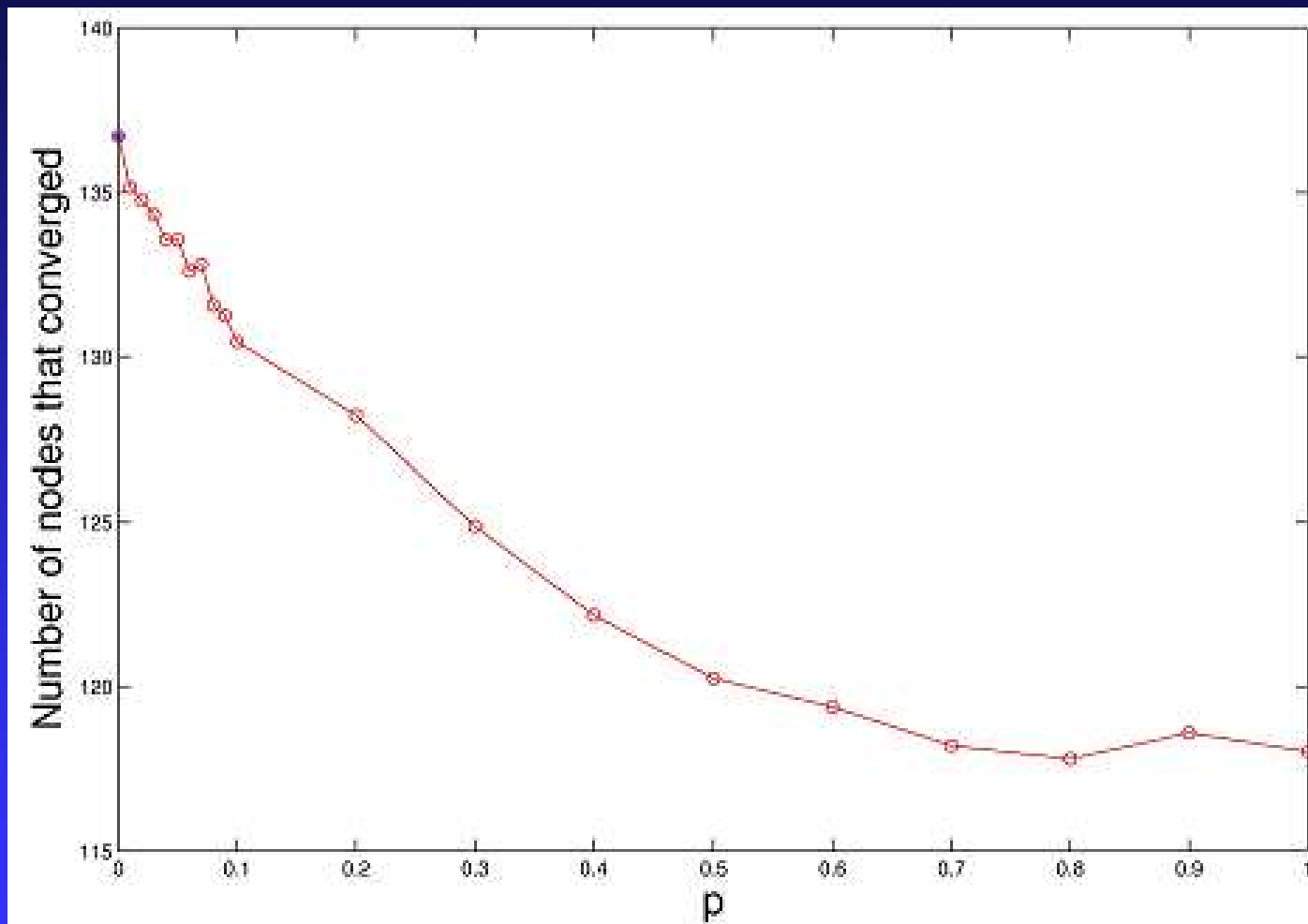
Total: 38.000 runs



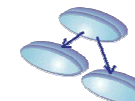
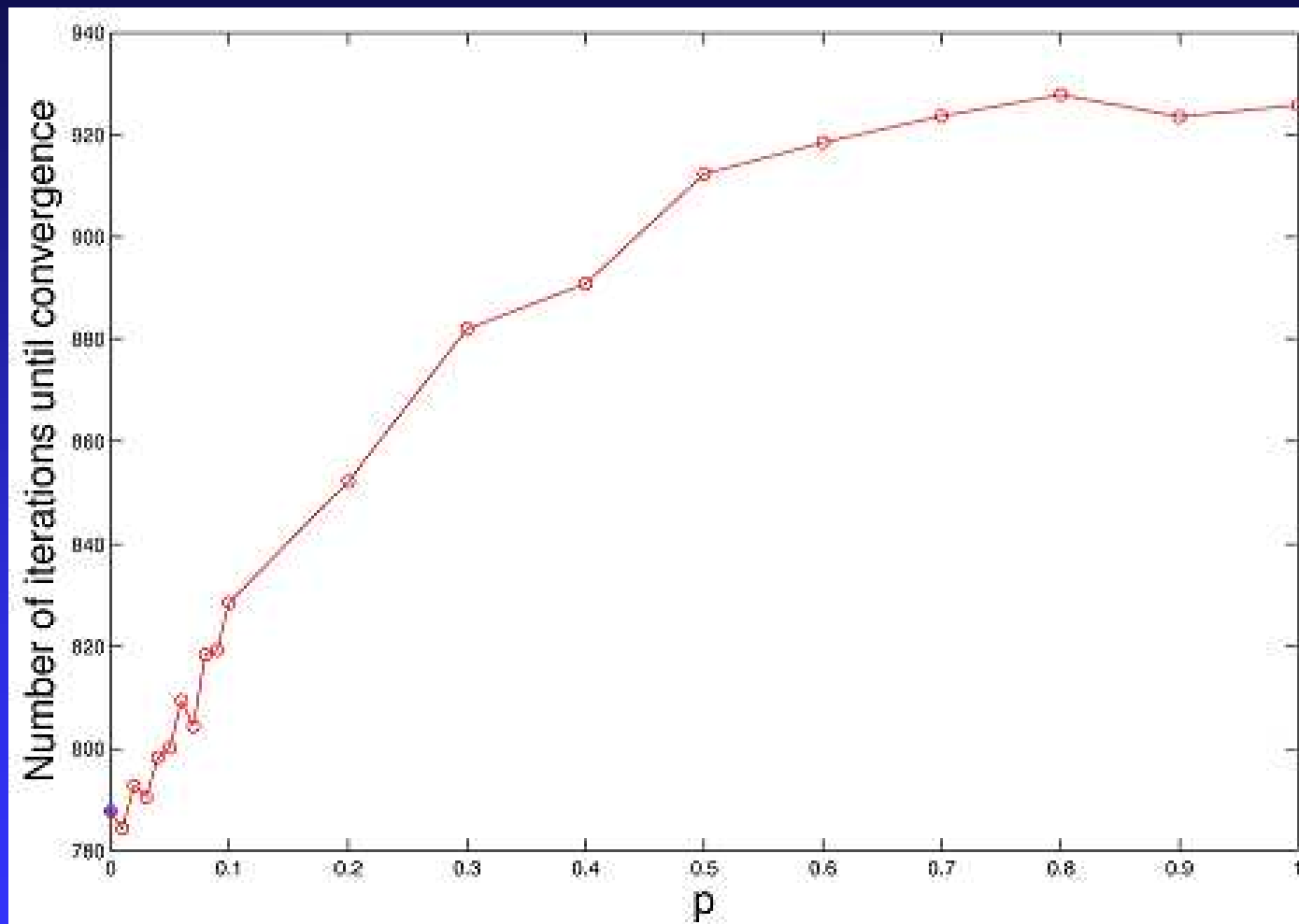
# Experiments. Arc rewiring (max)



# Experiments. Arc rewiring (max)

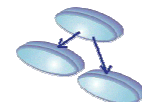
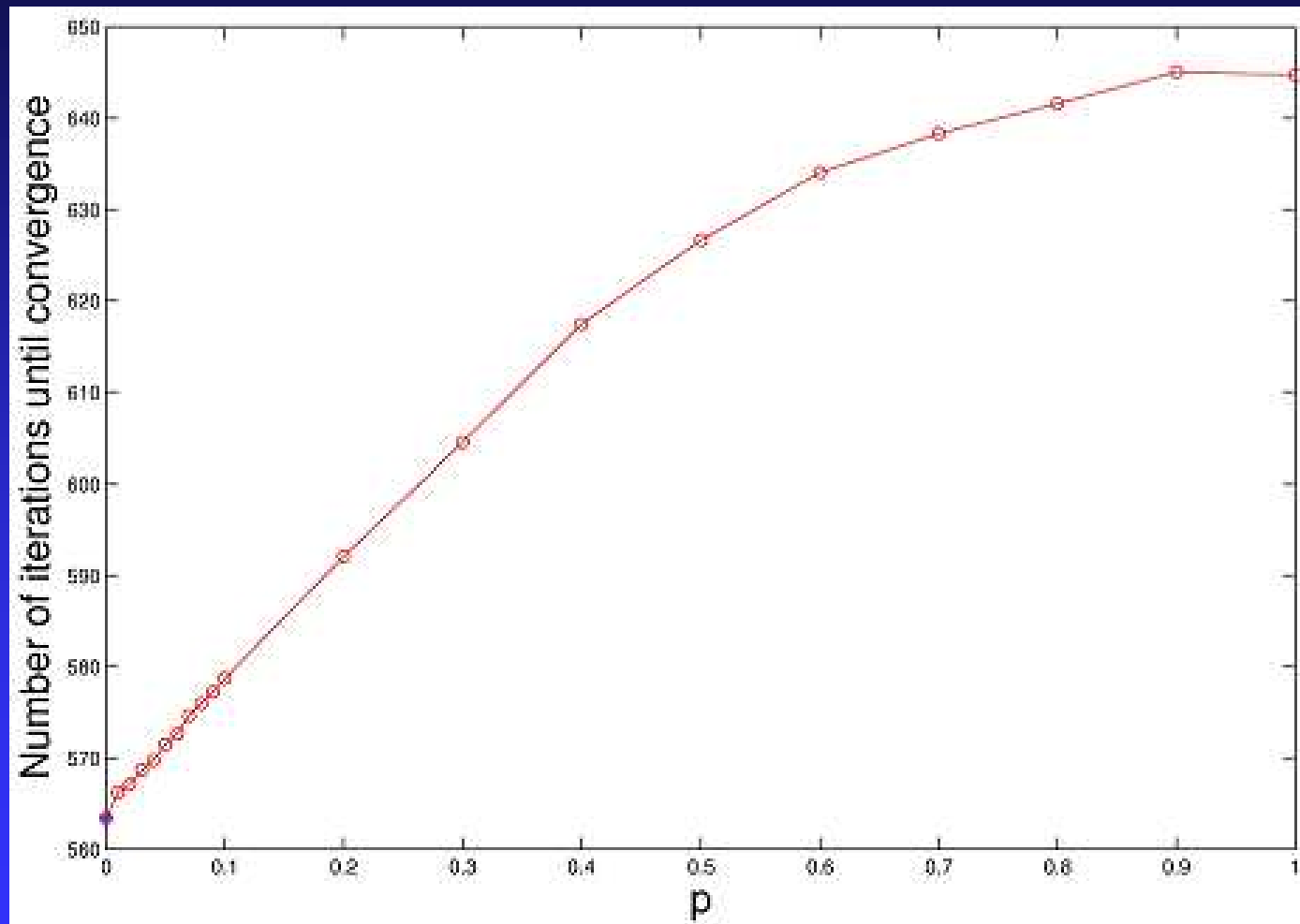


# Experiments. Arc rewiring (max)

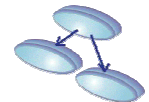
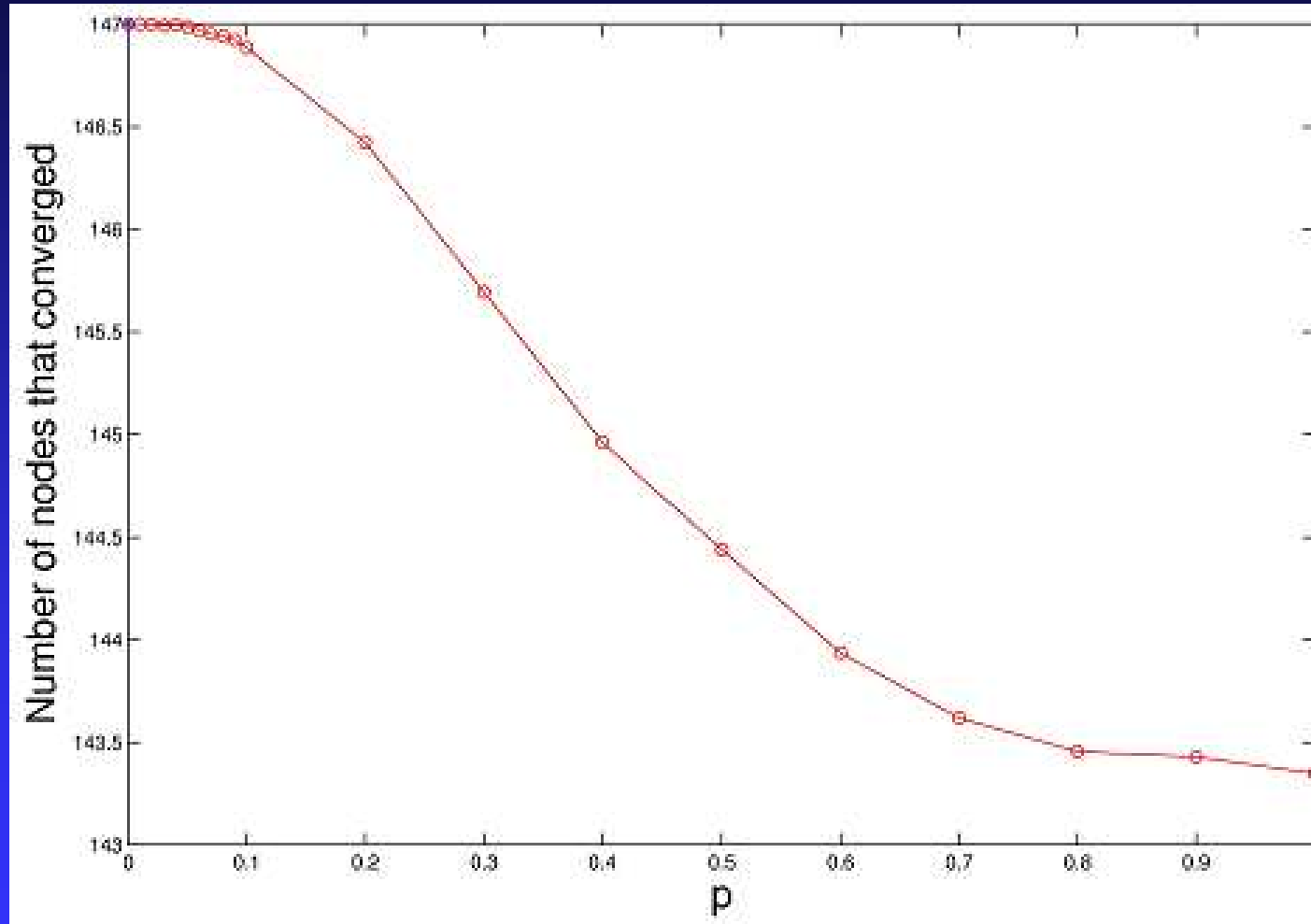




# Experiments. Arc rewiring (sum)

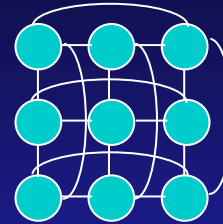


# Experiments. Arc rewiring (sum)

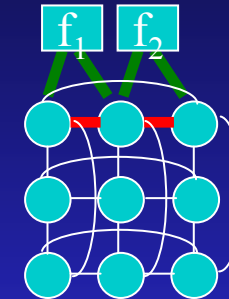


# Experiments. Adding shortcuts

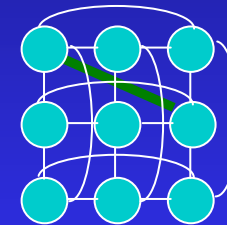
Starting from a grid (7x7)



50 sets of random functions for the grid



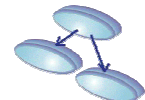
10 arcs will be added  
Random, Max. dist, Min. dist.



50 instances

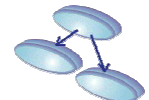
Sum-product and Max-product

Total: 15.000 runs



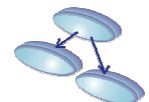
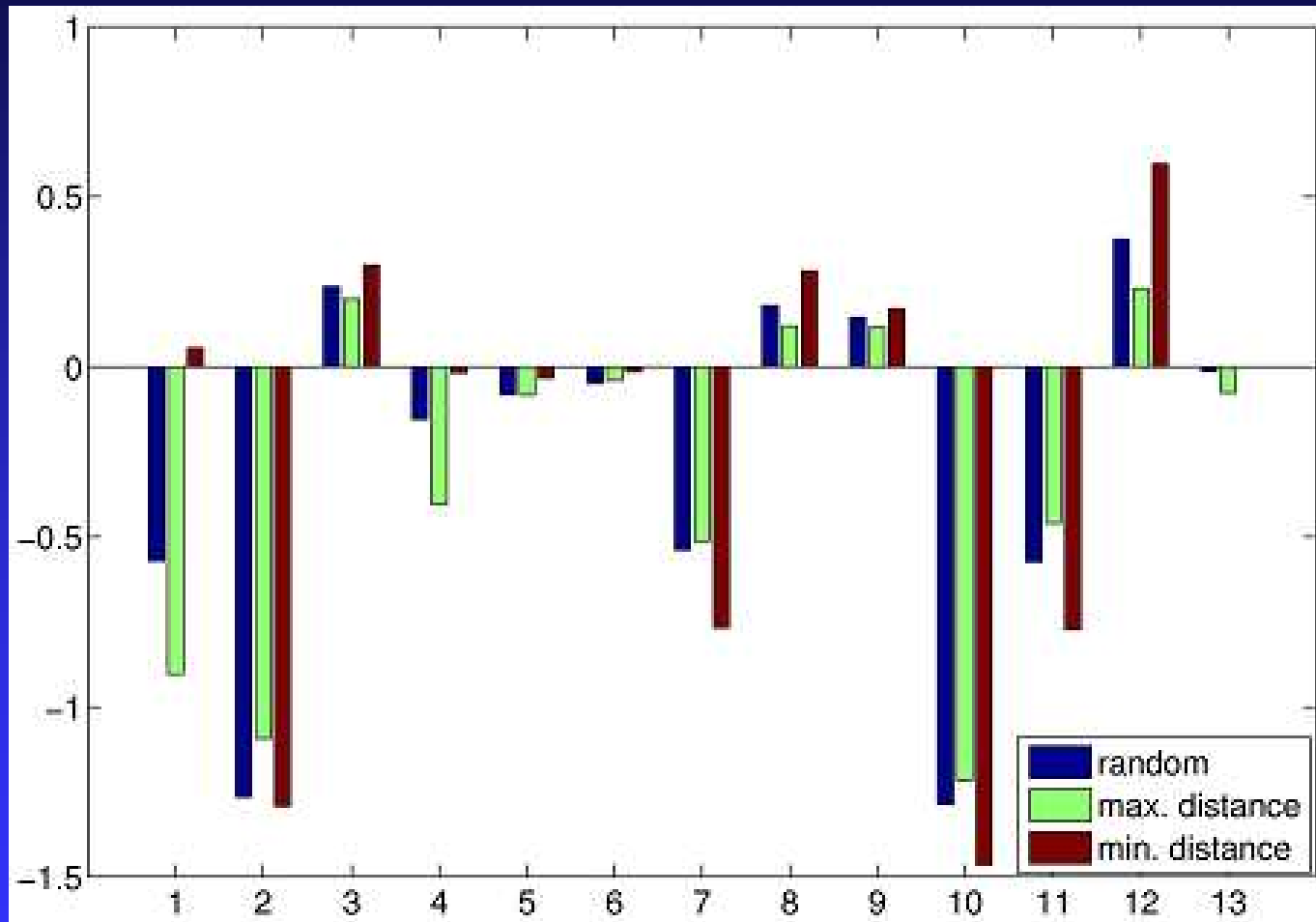
# Experiments. Adding shortcuts (max)

- Compare to the value of the original grid
  - ◆ Better in 9, 9, and 10 of the instances
  - ◆ Equal in 22, 22, and 24 of the instances
  - ◆ We completed some statistical tests to check differences between the three methods

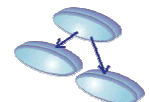
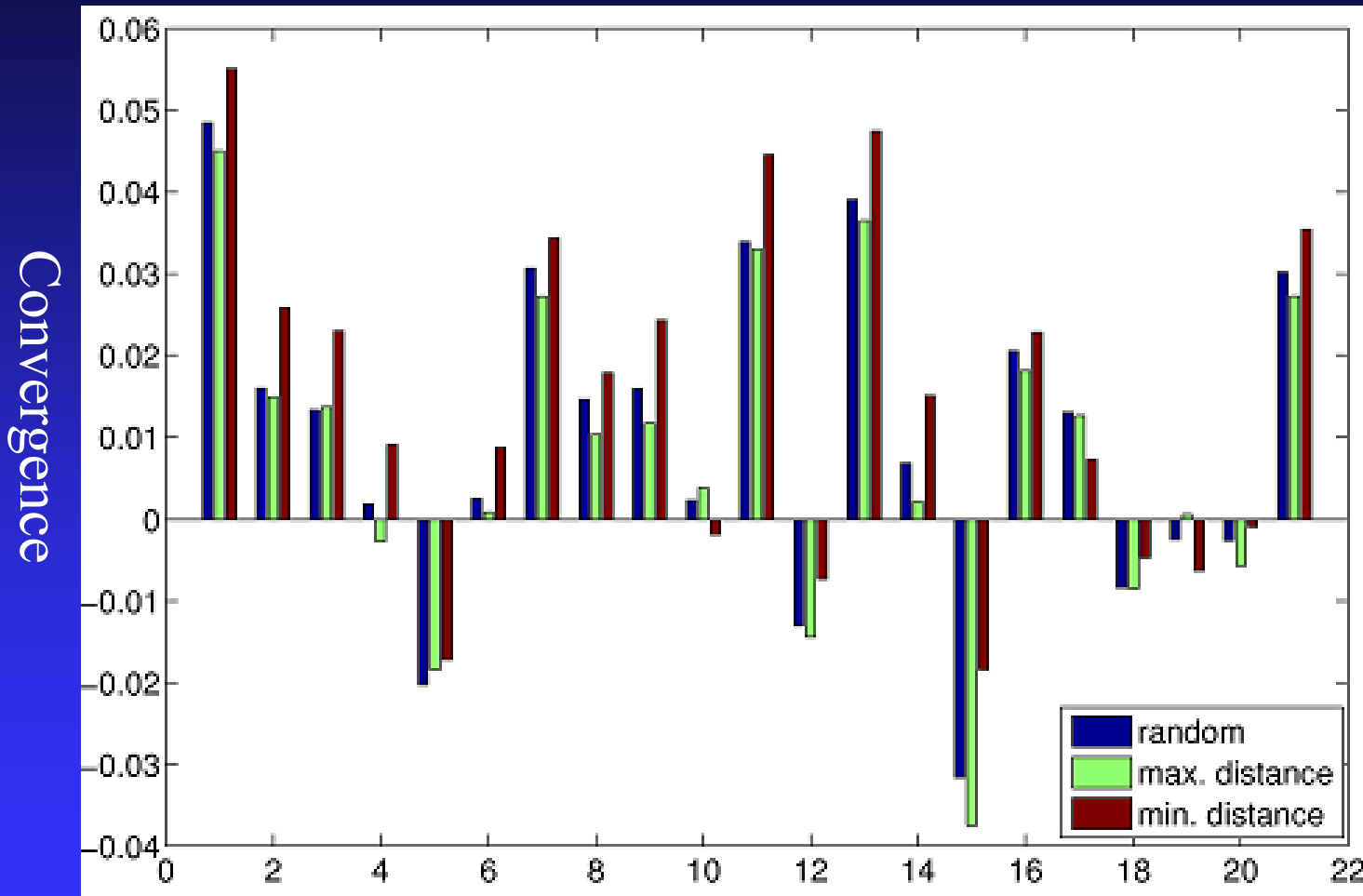


# Experiments. Adding shortcuts (max)

Function value

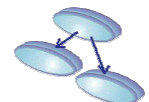
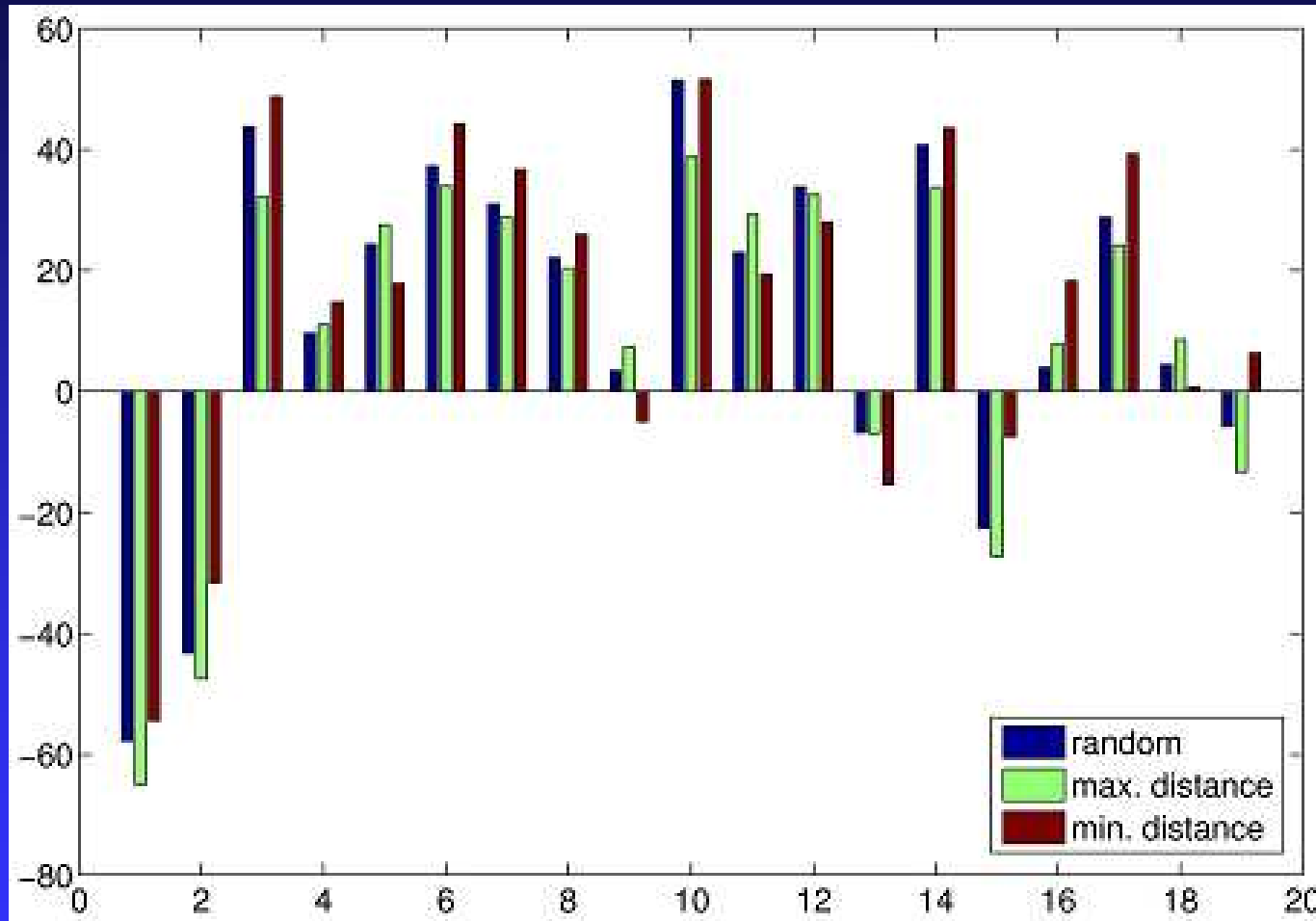


# Experiments. Adding shortcuts (max)



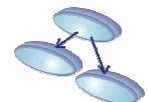
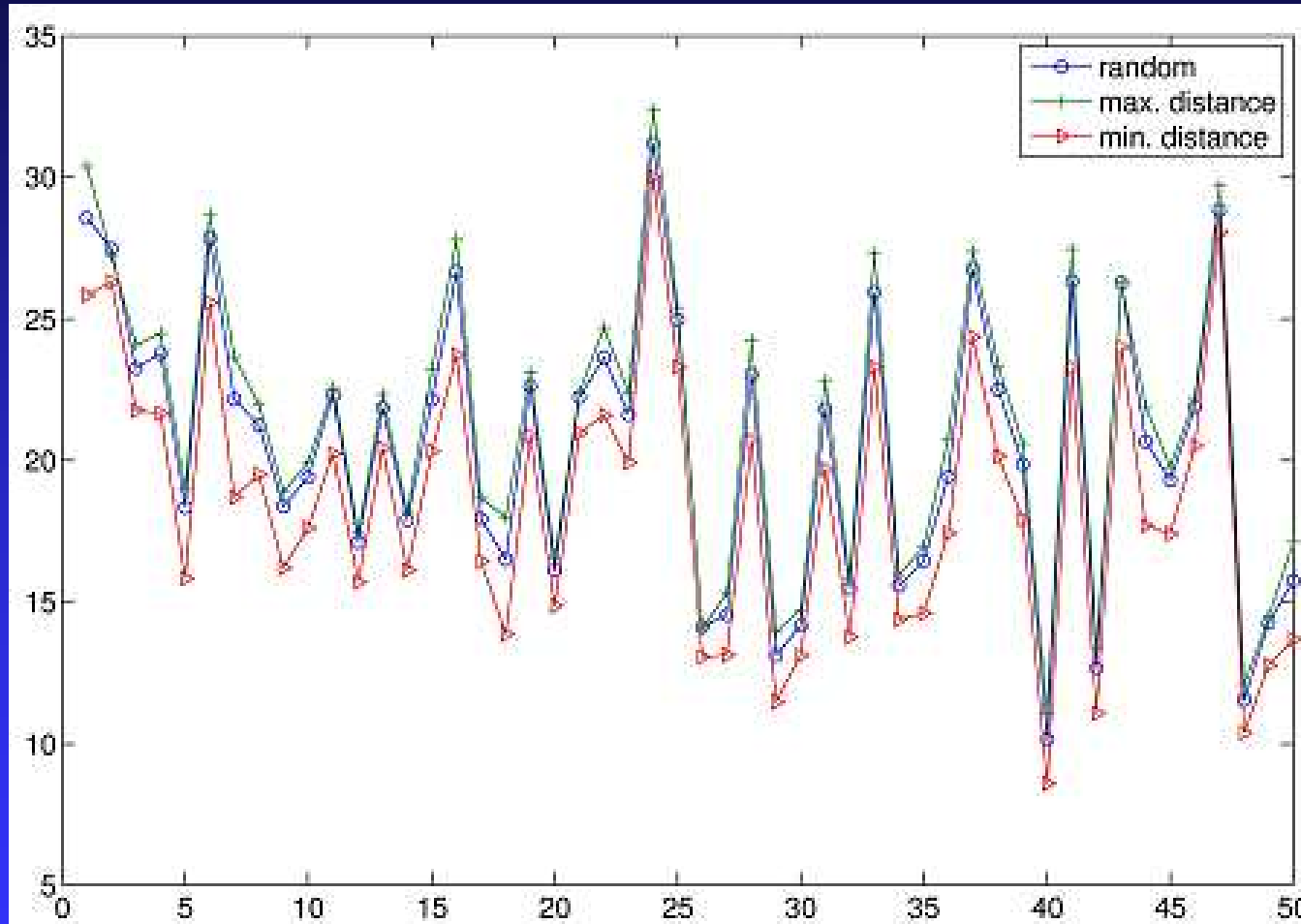
# Experiments. Adding shortcuts (max)

Iterations



# Experiments. Adding shortcuts (sum)

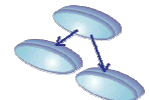
Iterations





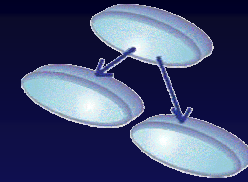
# Conclusions

- Empirical analysis of LBP in different topologies
  - ◆ Rewiring
    - ◆ Finding optimal solutions is harder as  $p$  increases
  - ◆ Adding shortcuts
    - ◆ Changes dynamics of LBP
    - ◆ Min distance seems to be more promising
    - ◆ On-line method?





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Thank you !!

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