

# Solving CLQG Influence Diagrams Using Arc-Reversal Operations in a Strong Junction Tree

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# Motivation

The influence diagram is a compact graphical model representation supporting decision making under uncertainty

- most architectures consider only the discrete case

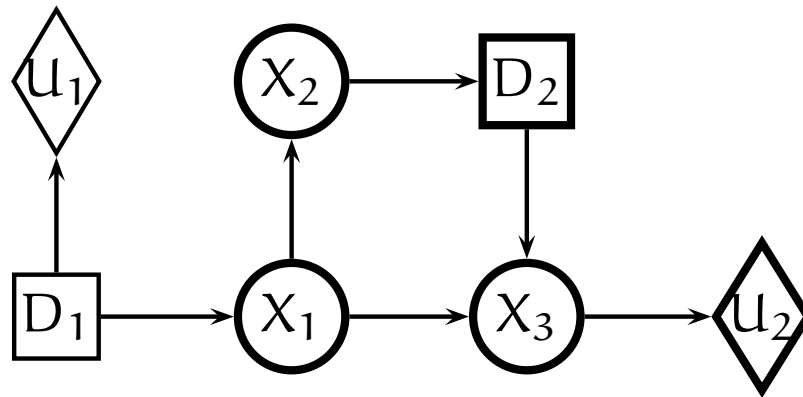
Decision problems often involve reasoning about entities of both discrete and continuous nature

- the problem of solving CLQG influence diagrams has received only limited attention

We present an architecture for representation and efficient, exact solution of CLQG influence diagrams using arc-reversal operations in Lazy Propagation

# CLQG Influence Diagrams

A CLQG ID  $\mathcal{N} = (\mathcal{X}, \mathcal{G}, \mathcal{P}, \mathcal{F}, \mathcal{U})$  consists of a graph  $\mathcal{G}$  over chance, decision, and utility nodes, a set of probability functions, and a set of utility functions



We consider CLQG IDs with a additively decomposing utility function

- for  $X \in \Gamma_C$  we have  $f(Y|Z = z, I = i) = \mathcal{N}(\alpha(i) + \beta(i)z, \sigma^2(i))$
- discrete chance and decision nodes can only have discrete parents
- $U(x, i) = \sum_{\psi \in \Psi} \psi$  is of the form  $x^T Q(i)x + R(i)x + S(i)$

# Solving CLQG Influence Diagram

The variables of  $\mathcal{N}$  induce an expected UF:

$$EU(\mathcal{X}) = P(\Delta_C | \Delta_D) \cdot f(\Gamma_C | \Delta, \Gamma_D) \cdot \sum_{u \in \mathcal{U}} u. \quad (1)$$

An optimal strategy can be identified by eliminating variables from (1) in the reverse time order.

- The elimination is performed using a sequence of AR operations and barren node eliminations
- The calculations are organized in a strong junction tree

# The AR Operation

The edge  $(X_i, X_j)$  is reversed by setting

$$p(X_j | Z_1, \dots, Z_n) = \sum_{X_i} p(X_j | X_i, Z_1, \dots, Z_n) p(X_i | Z_1, \dots, Z_n),$$

$$p(X_i | X_j, Z_1, \dots, Z_n) = \frac{p(X_j | X_i, Z_1, \dots, Z_n) p(X_i | Z_1, \dots, Z_n)}{p(X_j | Z_1, \dots, Z_n)}.$$

The edge  $(Y_i, Y_j)$  is reversed by setting

$$Y_i | Z_1, \dots, Z_n \sim \mathcal{N}((\alpha_{Y_i} + \beta_{Y_j}) + \sum_{i=1}^n (\beta_i + \delta_i) Z_i, \sigma_{Y_i}^2 + \beta_{Y_j}^2 \sigma_{Y_j}^2),$$

$$Y_j | Y_i, Z_1, \dots, Z_n \sim \mathcal{N}(\mu, \sigma^2), \text{ where}$$

$$\mu = \frac{\alpha_{Y_j} \sigma_{Y_i}^2 + \alpha_{Y_i} \beta_{Y_j} \sigma_{Y_j}^2 + \beta_{Y_j} \sigma_{Y_j}^2 Y_i + \sum_{i=1}^n (\delta_i \sigma_{Y_i}^2 - \beta_i \beta_{Y_j} \sigma_{Y_j}^2) Z_i}{\sigma_{Y_i}^2 + \beta_{Y_j}^2 \sigma_{Y_j}^2}, \sigma^2 = \frac{\sigma_{Y_j}^2 \sigma_{Y_i}^2}{\sigma_{Y_i}^2 + \beta_{Y_j}^2 \sigma_{Y_j}^2}$$

The AR operation is basically Bayes' rule and it corresponds to reversing an arc in the graph  $\mathcal{G}$

A potential is a triple  $\pi = (\mathcal{P}, \mathcal{F}, \mathcal{U})$  over probability potentials, densities, and utility functions

- combination  $\pi_{W_1} \otimes \pi_{W_2} = (\mathcal{P}_1 \cup \mathcal{P}_2, \mathcal{F}_1 \cup \mathcal{F}_2, \mathcal{U}_1 \cup \mathcal{U}_2)$ .
- projection of  $\pi_W = (\mathcal{P}_W, \mathcal{F}_W, \mathcal{U}_W)$  to a subset  $V \subseteq W$  denotes the potential  $\pi_V = \pi_W^{\downarrow V} = (\mathcal{P}_V, \mathcal{F}_V, \mathcal{U}_V)$  obtained by performing a sequence of variable eliminations of  $W \setminus V$

Solving a CLQG ID involves combination and projection over potentials

# Marginalization

Computing  $\pi = \pi^{\downarrow \text{dom}(\pi) - \{X\}} = (\mathcal{P}_V, \mathcal{F}_V, \mathcal{U}_V)$  includes marginalization of

- $X \in \Delta_C$ : make barren and set  $\pi_{\text{dom}(\pi) - \{X\}}^* = (\mathcal{P}^*, \emptyset, \mathcal{U}^*)$  where

$$\mathcal{P}^* = \mathcal{P}_X \setminus \{p(X|\mathbf{C}(X)) \in \mathcal{P}_X\},$$

$$\mathcal{U}^* = \mathcal{U} \setminus \mathcal{U}_X \cup \{(p(X|\mathbf{C}(X))) \cdot \sum_{u \in \mathcal{U}_X} u\}^{\downarrow \mathbf{C}(X)},$$

- $X \in \Gamma_C$ : make barren and set  $\pi_{\text{dom}(\pi) - \{X\}}^* = (\mathcal{P}, \mathcal{F}^*, \mathcal{U}^*)$  where

$$\mathcal{F}^* = \mathcal{F}_X \setminus \{f(X|\mathbf{C}(X)) \in \mathcal{F}_X\},$$

$$\mathcal{U}^* = \mathcal{U} \setminus \mathcal{U}_X \cup \{(f(X|\mathbf{C}(X))) \cdot \sum_{u \in \mathcal{U}_X} u\}^{\downarrow \mathbf{C}(X)}.$$

- $X \in \Delta_D$ : set  $\pi_{\text{dom}(\pi) - \{X\}}^* = (\emptyset, \emptyset, \mathcal{U} \setminus \mathcal{U}_X \cup \{\max_D \sum_{u \in \mathcal{U}_X} u\})$

- $X \in \Gamma_D$ : set  $\pi_{\text{dom}(\pi) - \{X\}}^* = (\emptyset, \emptyset, \mathcal{U} \setminus \mathcal{U}_X \cup \{(\sum_{u \in \mathcal{U}_X} u)^{\downarrow \{Z_1, \dots, Z_n\}}\})$

The main contribution is the use of uni-variate CLG distributions only

# Lazy Propagation (LP)

## Lazy Propagation

- an inference architecture based on message passing in a strong junction tree  $\mathcal{T}$ 
  - $\mathcal{T}$  guides the elimination process. It is constructed by moralization and strong triangulation
- Initialization of  $\mathcal{T}$ : the core of *lazy* evaluation is to maintain potential decompositions until combination becomes mandatory by variable elimination
  - potentials assigned to a clique are not combined
- Message passing in  $\mathcal{T}$ : messages  $\pi_{A \rightarrow B}$  are computed by elimination of variables
  - decision variables are eliminated by maximization
  - chance variables are eliminated by summation/integration



# Lazy Propagation (LP)

Evaluation of a CLQG ID using Lazy propagation in a strong junction tree

- after initialization each clique  $C$  holds a potential  $\pi_C = (\mathcal{P}, \mathcal{F}, \mathcal{U})$
- message passing  $\pi_{A \rightarrow B} = \left( \pi_A \otimes \left( \otimes_{C \in \text{ne}(A) \setminus \{B\}} \pi_{C \rightarrow A} \right) \right)^{\downarrow B}$
- local computation enables exploitation of barren variables and independence relations between variables

Policy optimization is performed as part of message passing

Main contributions

- AR operations and barren node eliminations as projection operation
- illustrate use of distributive law
- illustrate advantage of decomposition
- performance evaluation

# Distributive Law

Different researchers have exploited that the distributive law of algebra (DL) can be exploited in the solution process

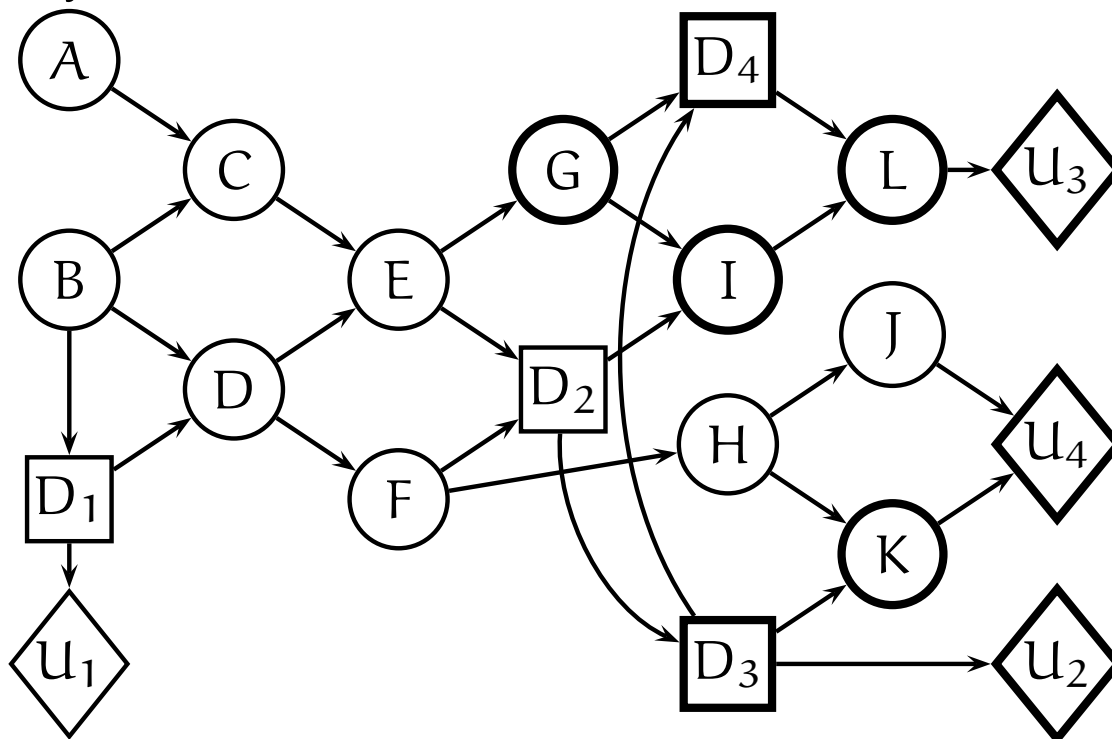
$$U(Y, T, Z) = \sum_X P(X) (U(X, Y, Z) + U(X, T)).$$

Using DL the expression is rewritten:

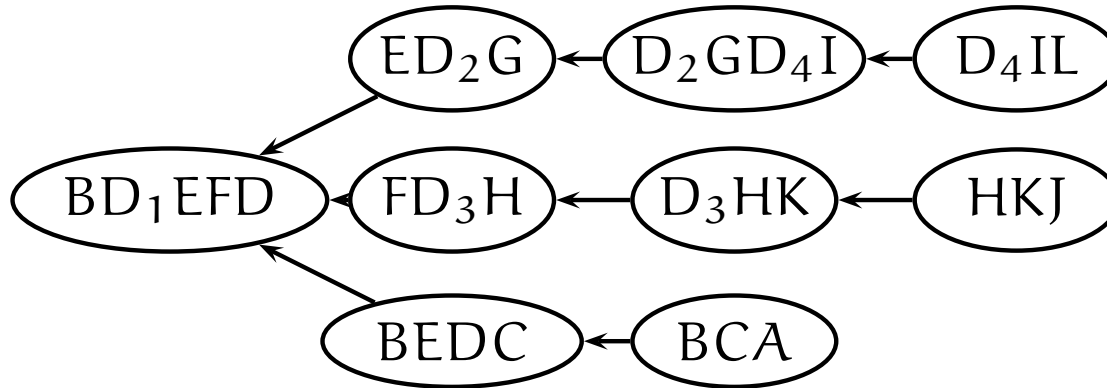
$$U(Y, Z) + U(T) = \sum_X P(X)U(X, Y, Z) + \sum_X P(X)U(X, T).$$

# Decomposition of Potentials

The CLQG ID by Jensen, Jensen & Dittmer



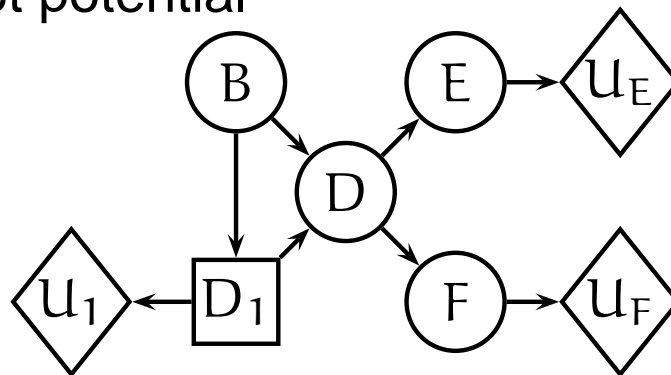
# Strong Junction Tree of CLQG ID



At the root we may compute (more efficiently)

$$EU(\hat{\Delta}) = \sum_B P(B) \max_{D_1} (U_1(D_1) + \sum_D P(D|B, D_1) (\sum_E P(E|D)U(E) + \sum_F P(F|D)U(F)))$$

Domain graph of root potential



# Performance Analysis - Random Networks

$  \mathcal{X}  $	Time		Space	
	LARP	HDE	LARP	HDE
20	4.27	N/A	1,953,125	N/A
20	0.93	1.25	390,625	1,953,125
20	0.03	0.24	3,125	390,625
25	0.13	N/A	15,625	N/A
25	0.64	1.74	78,125	1,953,125
50	4.67	10.16	1,048,576	8,388,608
50	24.31	N/A	4,194,304	N/A
50	7.22	28.64	1,048,576	16,777,216

CLQG IDs have discrete variables only and  $|\mathcal{X}| \leq 25$  implies  $||X|| = 5$  while  $|\mathcal{X}| = 50$  implies have  $||X|| = 2$

# Performance Analysis - JJD network

Different versions of the CLQG ID network of Jensen, Jensen & Dittmer

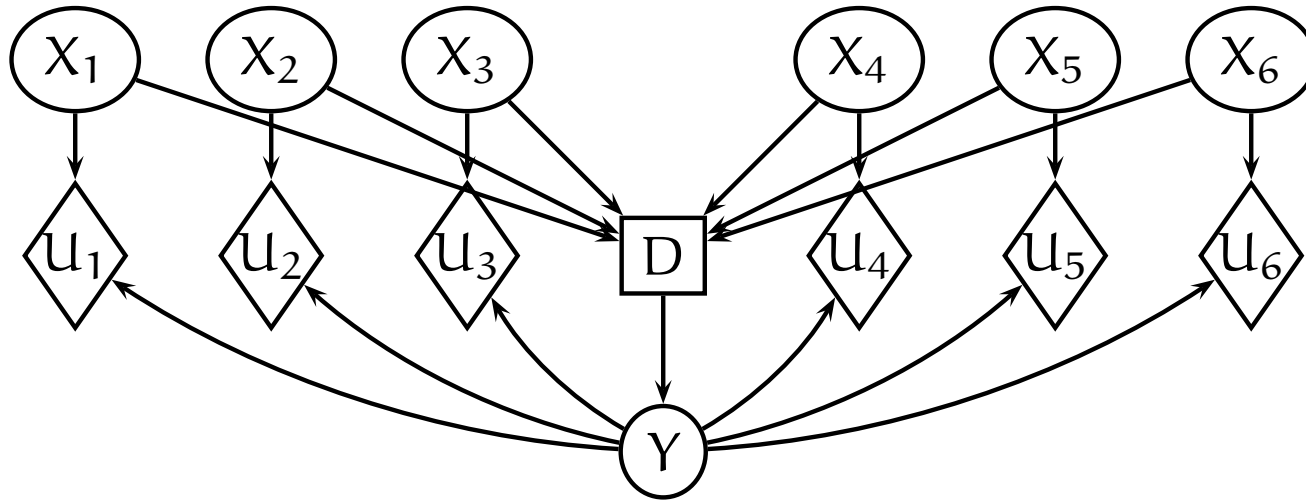
<i>jjd</i>	$ \mathcal{C} $	$\max_{C \in \mathcal{C}} s(C)$	$s(C)$
<i>d</i>	9	9,765,625	10,640,625
<i>m</i>	9	9,765,625	10,188,826
<i>c</i>	9	1	1

Performance evaluation

<i>jjd</i>	Time		Space	
	HDE	LARP	HDE	LARP
<i>d</i>	3.87	0.53	9,765,625	390,625
<i>m</i>	-	0.35	-	390,625
<i>c</i>	-	0.03	-	1

# Performance Analysis - DL

A naive example with  $\|Y\| = 100$ ,  $\|X_i\| = 5$  and  $\|D\| = 10$



The (Strong) junction tree is a single clique

Using HDE, LARP and LARP with DL the average time costs in seconds (over ten runs) are 2.91, 16.73, and 0.49.

# Conclusion

The main contributions of the paper is an architecture for solving CLQG IDs using arc-reversal in Lazy propagation

- Results of a preliminary performance evaluation are promising
- Future work includes extending the architecture to support the LIMID representation

Related work includes Lauritzen&Jensen on evidence propagation in CLG BNs // Madsen&Jensen and Madsen&Nilsson on solving influence diagrams by *lazy* evaluation // Poland and Kenley&Shachter on linear-quadratic Gaussian influence diagrams // Madsen&Jensen on solving CLQG IDs // Cobb&Shenoy on MTEs